

---

# **Computer Vision & Digital Image Processing**

Morphological Image Processing

---

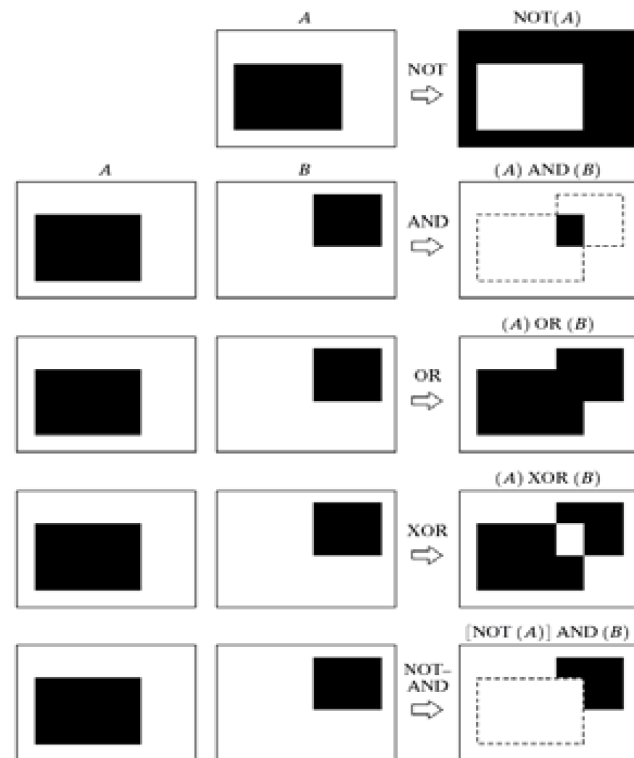
# Introduction

---

- *Morphology* – a branch of biology concerned with the form and structure of plants and animals
  - *Mathematical morphology* – a tool for extracting image components useful in the representation and description of image shape including:
    - Boundaries
    - Skeletons
    - Convex hull
  - We will also look at morphological techniques for
    - Filtering
    - Thinning
    - Pruning
-

# Logical Operations Involving Binary Images

- Principal logic operations
  - AND
  - OR
  - NOT (COMPLEMENT)
- Functionally complete
  - Combined to form any other logic operation
- Logic operations described have a one-to-one correspondence with the set operations intersection, union and complement
  - Logic operations are restricted to binary images (not the case for general set operations)



# Basic Concepts from Set Theory

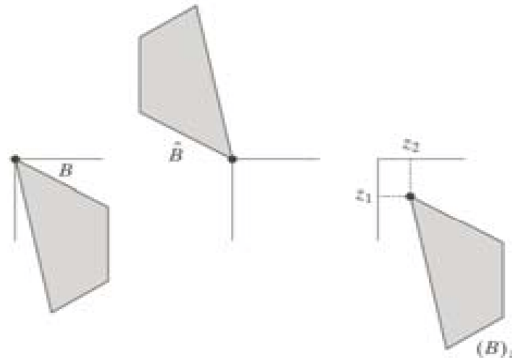
---

- The *reflection* of set  $B$  is defined as

$$\hat{B} = \{w \mid w = -b, \text{ for } b \in B\}$$

- The *translation* of set  $B$  by point  $z = (z_1, z_2)$  is defined as

$$(B)_z = \{c \mid c = b + z, \text{ for } b \in B\}$$



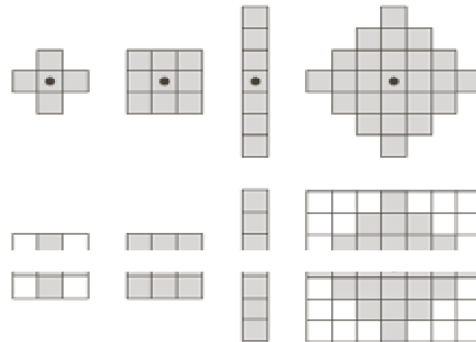
a b c

**FIGURE 9.1**  
(a) A set, (b) its reflection, and (c) its translation by  $z$ .

---

# Structuring Elements

- Set reflection and translation are used extensively in morphological operations based on *structuring elements* (SE)
- An SE is a small set (or subimage) used to “probe” an area of interest for certain properties
  - May be of arbitrary shape and size
  - In practice an SE is generally a regular geometric shape (square, rectangle, diamond, etc.)
  - Generally padded to a rectangular array for image processing



**FIGURE 9.2** First row: Examples of structuring elements. Second row: Structuring elements converted to rectangular arrays. The dots denote the centers of the SEs.

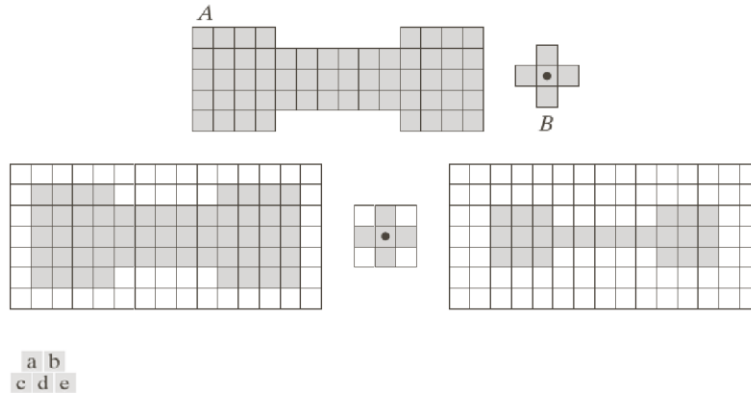
# Structuring Elements (continued)

---

- Two-dimensional, or flat, structuring elements consist of a matrix of 0's and 1's, typically much smaller than the image being processed.
  - The center pixel of the structuring element, called the origin, identifies the pixel of interest--the pixel being processed.
  - The pixels in the structuring element containing 1's define the neighborhood of the structuring element.
-

## Operation with a Structuring Element (example)

---



**FIGURE 9.3** (a) A set (each shaded square is a member of the set). (b) A structuring element. (c) The set padded with background elements to form a rectangular array and provide a background border. (d) Structuring element as a rectangular array. (e) Set processed by the structuring element.

---

# Dilation

---

- With  $A$  and  $B$  as sets in  $Z^2$ , the *dilation* of  $A$  by  $B$ , denoted  $A \oplus B$ , is defined as

$$A \oplus B = \{z \mid (\hat{B})_z \cap A \neq \emptyset\}$$

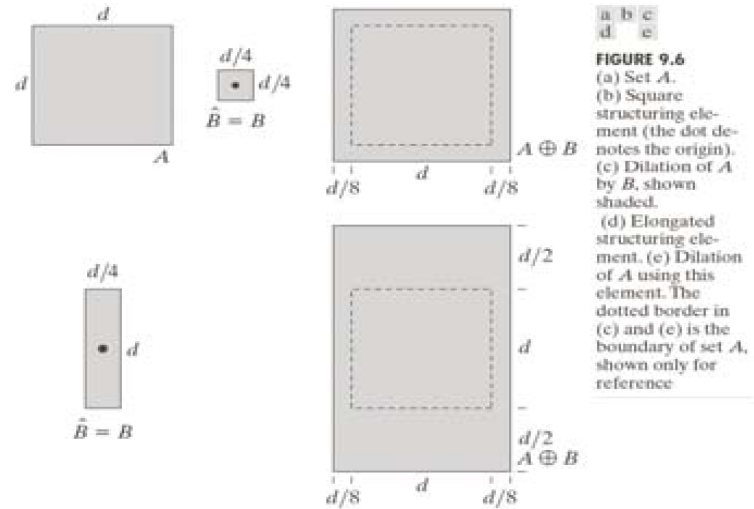
- This formulation is based on the reflection of  $B$  about its origin and shifting this reflection by  $z$
- The dilation of  $A$  by  $B$  is the set of all *displacements*,  $z$ , such that  $B$  and  $A$  overlap by at least one element
- Therefore, another expression for the *dilation* of  $A$  by  $B$  is

$$A \oplus B = \{z \mid [(\hat{B})_z \cap A] \subseteq A\}$$

- Set  $B$  is the *structuring element*

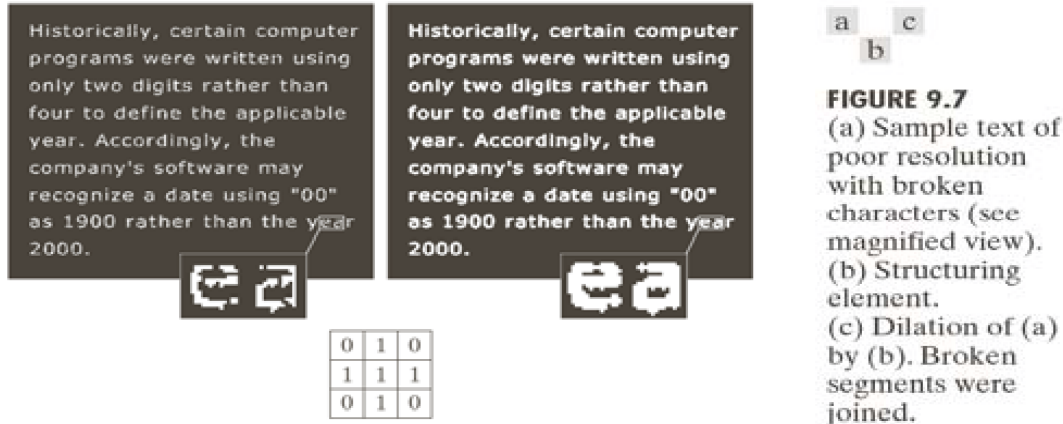
# Dilation Example

- $B = \hat{B}$  because  $B$  is symmetric with respect to its origin
- The dashed line shows the original set  $A$  and the solid boundary shows the limit beyond which any further displacements of the origin of  $\hat{B}$  by  $z$  would cause the intersection of  $\hat{B}$  and  $A$  to be empty
- All points inside this boundary constitute the dilation of  $A$  by  $B$
- The second case shows more dilation vertically than horizontally



# Dilation Application

- One simple application of dilation is for bridging gaps
- In the image below, the maximum break length is two pixels
- Although low pass filtering can be used to accomplish the same task, this generates a gray-scale image that must then be thresholded to produce a resulting binary image



# Erosion

---

- With  $A$  and  $B$  as sets in  $\mathbb{Z}^2$ , the *erosion* of  $A$  by  $B$ , denoted  $A \ominus B$ , is defined as

$$A \ominus B = \{z \mid (B)_z \subseteq A\}$$

- In words, the erosion of  $A$  by  $B$  is the set of all points  $z$  such that  $B$ , translated by  $z$ , is contained in  $A$
- Dilation and erosion are duals of each other with respect to set complementation and reflection
- Therefore

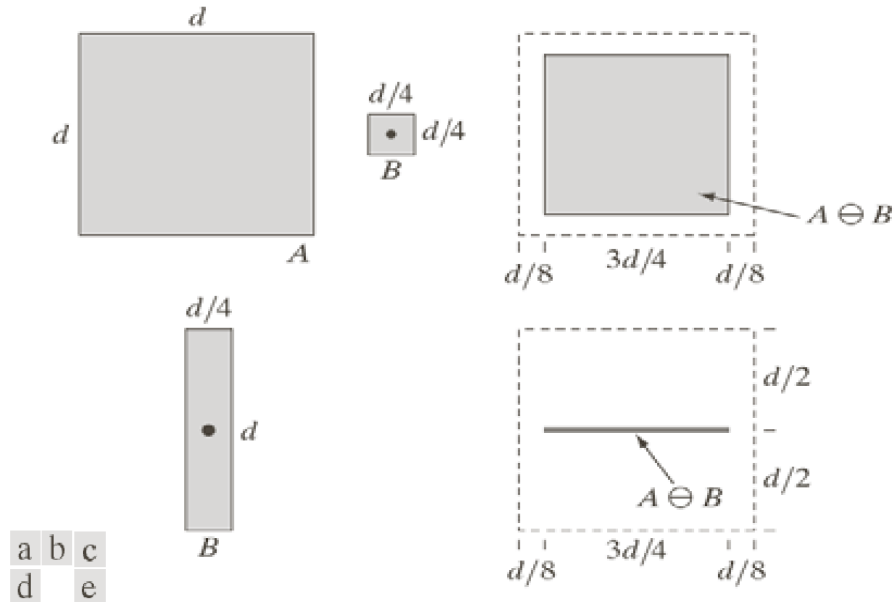
$$(A \ominus B)^c = A^c \oplus \hat{B}$$

and

$$(A \oplus B)^c = A^c \ominus \hat{B}$$

---

# Erosion Example

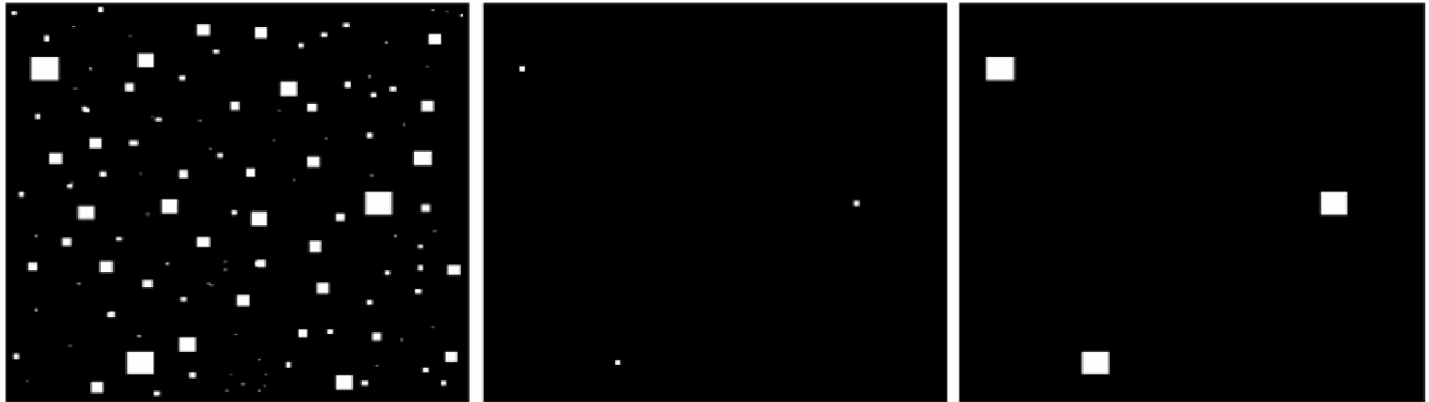


**FIGURE 9.4** (a) Set  $A$ . (b) Square structuring element,  $B$ . (c) Erosion of  $A$  by  $B$ , shown shaded. (d) Elongated structuring element. (e) Erosion of  $A$  by  $B$  using this element. The dotted border in (c) and (e) is the boundary of set  $A$ , shown only for reference.

# Erosion and Dilation Application

---

- One simple application of erosion is for eliminating irrelevant detail (in terms of size) from a binary image
- Note: In general, dilation does not restore fully the eroded objects



Erosion of a binary image with a 13x13 size structuring element and subsequent dilation of the result with the same element.

---

## Opening and Closing

---

- Morphological *opening* generally
    - Smooths the contour of an object
    - Breaks narrow isthmuses
    - Eliminates thin protrusions
  - Morphological *closing* generally
    - Smooths contour sections
    - Fuses narrow breaks and long thin gulfs
    - Eliminates small holes
    - Fills gaps in a contour
-

## Opening and Closing

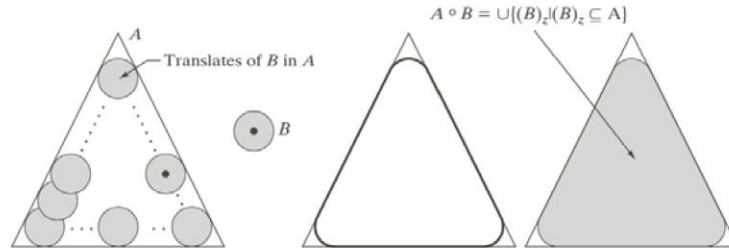
---

- The opening of set  $A$  by structuring element  $B$ , denoted  $A \circ B$ , is defined as
    - $A \circ B = (A \ominus B) \oplus B$
  - Thus, opening is defined as the erosion of  $A$  by  $B$  followed by a dilation of the result by  $B$
  - The closing of set  $A$  by structuring element  $B$ , denoted  $A \bullet B$ , is defined as
    - $A \bullet B = (A \oplus B) \ominus B$
  - Thus, closing is defined as the dilation of  $A$  by  $B$  followed by an erosion of the result by  $B$
-

## Opening: Geometric Interpretation

---

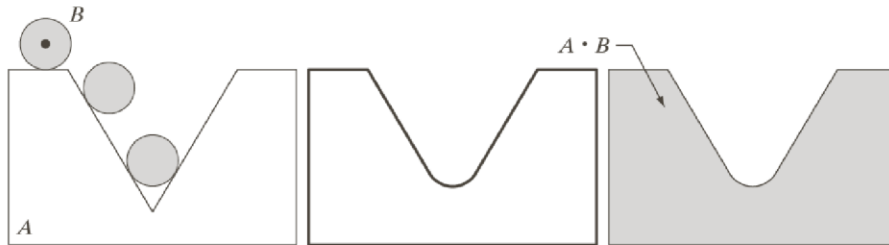
- Suppose the structuring element,  $B$ , is viewed as a rolling ball
- The boundary of  $A \circ B$  is established by all points in  $B$  that reach the *farthest* into the boundary of  $A$  as  $B$  is rolled about the *inside* of this boundary
- The opening of  $A$  by  $B$  is obtained by taking the union of all translates of  $B$  that fit into  $A$ 
  - $A \circ B = \cup \{(B)_z \mid (B)_z \subseteq A\}$



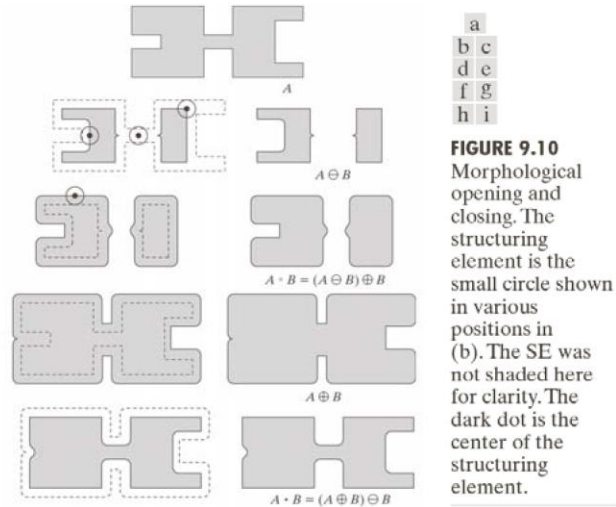
## Closing: Geometric Interpretation

---

- Suppose the structuring element,  $B$ , is viewed as a rolling ball
- The boundary of  $A \bullet B$  is established by all points in  $B$  that reach the *closest* to the boundary of  $A$  as  $B$  is rolled about the *outside* of this boundary
  - $A \bullet B = \{w \mid (B)_z \cap A \neq \emptyset \text{ for any translate of } (B)_z \text{ containing } w\}$



## Opening and Closing Examples



## Morphological Filtering

---

- Morphological operators can be used to construct filters similar in concept to spatial filters
- If the filtering objective in question is to eliminate noise and distort data of interest as little as possible, then a morphological filter consisting of an opening followed by a closing can be used
- Recall from the definitions of opening and closing that the more primitive operations of erosion and dilation are used

– Opening

$$A \circ B = (A \ominus B) \oplus B$$

erode                      dilate

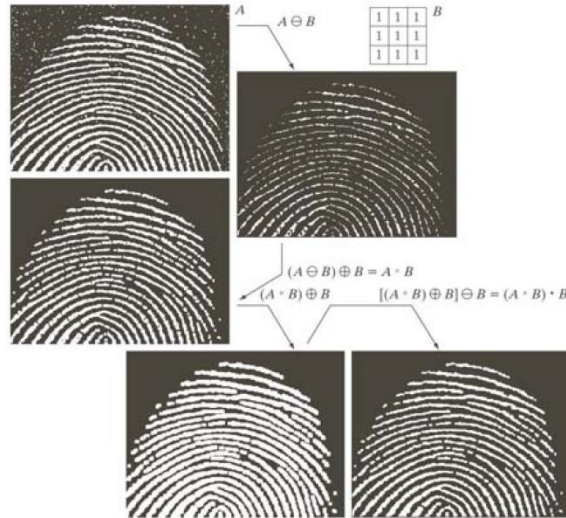
Closing

$$A \bullet B = (A \oplus B) \ominus B$$

dilata                      erode



# Morphological Filtering Example



a b  
d c  
e f

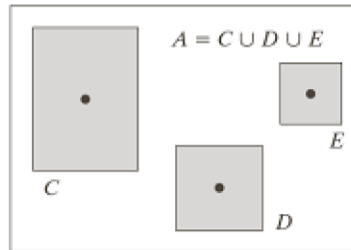
**FIGURE 9.11**

- (a) Noisy image.
  - (b) Structuring element.
  - (c) Eroded image.
  - (d) Opening of  $A$ .
  - (e) Dilation of the opening.
  - (f) Closing of the opening.
- (Original image courtesy of the National Institute of Standards and Technology.)

## Hit-or-Miss Transform

---

- The morphological hit-or-miss transform is a basic tool for shape detection
- The basic intent is to find the location of a known shape within a set of shapes
- Assume a set  $A$  consists of a set of shapes (subsets)  $C$ ,  $D$ , and  $E$
- It is desired to find the location of one of the shapes,  $D$
- Let the origin of each shape be its center of gravity



## Hit-or-Miss Transform

---

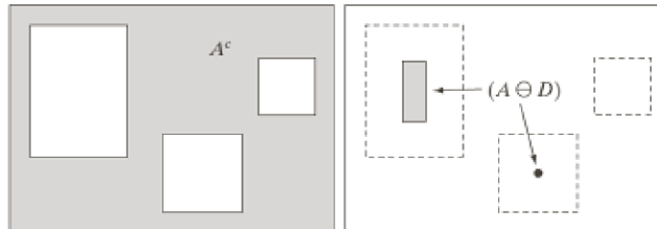
- Let  $D$  be enclosed by a small window,  $W$
- The *local background* of  $D$  with respect to  $W$  is defined as the set difference  $(W-D)$



## Hit-or-Miss Transform

---

- The complement of  $A$ ,  $A^c$ , is needed in the transform operation
- Let  $A$  be eroded by  $D$
- The erosion of  $A$  by  $D$  is the set of locations of the *origin* of  $D$ , such that  $D$  is completely contained in  $A$
- Viewed geometrically, this is the set of all locations of the origin of  $D$  at which  $D$  found a match (hit) in  $A$



# Hit-or-Miss Transform

- Erode the complement of  $A$ ,  $A^c$ , by the local background set ( $W-D$ )
- If we now compute the intersection of the two computed values, this give use the location of  $D$
- If  $B$  denotes the set composed of  $D$  and its background, the match (or set of matches) of  $B$  in  $A$ , denoted  $A^{\oplus}B$ , is
- $A^{\oplus}B = (A \ominus D) \cap [A^c \ominus (W-D)]$

